Outline

- Liouville's theorem
- Canonical coordinates
- Hamiltonian
- Symplecticity
- Symplectic integration
- Symplectification algorithm



Liouville's Theorem

In the local region of a particle, the particle density in phase space is constant provided that the particles move in a general field consisting of magnetic fields and of fields whose forces are independent of velocity.

• Density function = number of particles per unit volume of six-dimensional phase space

$$f(\vec{r},\vec{p},t)$$

• Particle current

$$\vec{J}_{6} = (f\vec{r}, f\vec{p}) = (f\vec{v}, f\vec{F})$$

• Continuity equation = preservation of the number of particles

$$\begin{split} \partial f / \partial t + \nabla_6 \cdot \vec{J}_6 &= 0 \\ \nabla_6 \cdot \vec{J}_6 &= \nabla \cdot (f \vec{\upsilon}) + \nabla_p (f \vec{F}) = (\nabla f) \cdot \vec{\upsilon} + f \underbrace{(\nabla \cdot \vec{\upsilon})}_0 + (\nabla_p f) \cdot \vec{F} + f (\nabla_p \cdot \vec{F}) \\ \nabla_p \cdot \vec{F} &= \underbrace{\nabla_p \cdot [\vec{g}(\vec{r}) + q \vec{\upsilon} \times \vec{B}(\vec{r})]}_0 = q \nabla_p \cdot (\vec{\upsilon} \times \vec{B}) = q \vec{B} \cdot (\nabla_p \times \vec{\upsilon}) - q \vec{\upsilon} \cdot \underbrace{(\nabla_p \times \vec{B})}_0 \\ \left[\nabla_p \times \left(\frac{\vec{p}}{\sqrt{p^2 c^2 + m^2 c^4}} \right) \right]_z = \frac{\partial}{\partial p_x} \left(\frac{p_y}{\sqrt{p^2 c^2 + m^2 c^4}} \right) - \frac{\partial}{\partial p_y} \left(\frac{p_x}{\sqrt{p^2 c^2 + m^2 c^4}} \right) = 0 \Rightarrow \\ \nabla_p \times \vec{\upsilon} = 0 \end{split}$$



Liouville's Theorem

 $\nabla_6 \cdot \vec{J}_6 = (\nabla f) \cdot \vec{\upsilon} + (\nabla_p f) \cdot \vec{F}$

• Continuity equation becomes

$$\partial f / \partial t + (\nabla f) \cdot \dot{\vec{r}} + (\nabla_p f) \cdot \dot{\vec{p}} = df / dt = 0$$

Theorem proved.

- Limitations and exceptions
 - Linear and non-linear mismatch \Rightarrow effective emittance growth
 - Velocity-dependent Coulomb interaction between individual particles: IBS, Touschek
 - Dissipative mechanisms
 - Radiation, radiation damping
 - Charge-exchange injection
 - Electron cooling
 - Stochastic cooling
- An immediate consequence of the theorem

$$\vec{Y} = \vec{T}(\vec{X}), \quad \Delta \vec{T} = \sum_{j=1}^{6} \frac{\partial \vec{T}}{\partial X_j} (\vec{0}) \Delta X_j, \quad \Delta Y_i = \sum_{j=1}^{6} \frac{\partial T_i}{\partial X_j} (\vec{0}) \Delta X_j = \sum_{j=1}^{6} M_{ij} \Delta X_j$$

Since the determinant of the Jacobian is a ratio of volumes

$$\det M = 1$$



Canonical Momentum and Vector Potential

Conservative force

$$\nabla \times \vec{F} = 0$$

• Lorentz force

$$\vec{F} = d\vec{p} / dt = q(\vec{E} + \vec{\upsilon} \times \vec{B})$$

can be velocity dependent and is not always conservative.

$$\nabla \times \vec{F} = \nabla \times d\vec{p} / dt = q[\nabla \times \vec{E} + \nabla \times (\vec{v} \times \vec{B})]$$

= $-q\partial \vec{B} / \partial t + q[(\vec{B} \cdot \nabla)\vec{v} - (\vec{v} \cdot \nabla)\vec{B} + (\nabla \cdot \vec{B})\vec{v} - (\nabla \cdot \vec{v})\vec{B}]$
= $-q\partial \vec{B} / \partial t - q(\vec{v} \cdot \nabla)\vec{B} = -qd\vec{B} / dt = -d(\nabla \times q\vec{A}) / dt \Rightarrow$
$$\nabla \times \frac{d\vec{p}}{dt} + \frac{d}{dt}(\nabla \times q\vec{A}) = \nabla \times \left[\frac{d}{dt}(\vec{p} + q\vec{A})\right] = 0$$

• Canonical momentum and conservative canonical force

$$\vec{P} = \vec{p} + q\vec{A}, \quad \vec{F}_{can} = d\vec{P} / dt$$



Hamiltonian

• Relativistic Hamiltonian of a free particle

$$H = \sqrt{p^2 c^2 + m^2 c^4}$$

• Hamiltonian in an electromagnetic field

$$\vec{B} = \nabla \times \vec{A}, \quad \vec{E} = -\nabla \phi - \partial \vec{A} / \partial t$$
$$H = \sqrt{(\vec{P} - q\vec{A})^2 c^2 + m^2 c^4} + q\phi$$

• Hamilton's equations

$$d\vec{P} / dt = -\nabla H, \quad d\vec{x} / dt = \nabla_P H$$

• Frenet-Serret curvilinear coordinate system

$$d\vec{l} = dr\,\hat{r} + rd\,\theta\,\hat{\theta} + dy\,\hat{y} = dx\,\hat{x} + \frac{r}{\rho}ds\,\hat{s} + dy\,\hat{y} = dx\,\hat{x} + dy\,\hat{y} + (1 + \frac{x}{\rho})ds\,\hat{s}$$

Hamiltonian becomes

$$H = \sqrt{m^2 c^4 + c^2 \left[p_x^2 + p_y^2 + \left(\frac{p_s}{1 + x / \rho} \right)^2 \right]}$$

$$H = c_{\sqrt{m^2 c^2 + (P_x - qA_x)^2 + (P_y - qA_y)^2 + (\frac{P_s - qA_s}{1 + x/\rho})^2} + q\phi$$



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s-Hamiltonian

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Poincaré-Cartan invariant under a canonical variable transformation

$$\vec{P} \cdot d\vec{r} - Hdt = inv$$

$$P_x dx + P_y dy + P_s ds - Hdt = P_x dx + P_y dy + (-H)dt - (-P_s)ds$$

$$= P_x dx + P_y dy + (-U)dt - H_s ds$$

 $\vec{\mathbf{D}}$ $1 \rightarrow$

• Hamiltonian with the longitudinal coordinate as the independent variable

$$H_{s} = -P_{s}(x, P_{x}, y, P_{y}, t, -U; s)$$

= $-qA_{s} - \left(1 + \frac{x}{\rho}\right)\sqrt{\left(\frac{U - q\phi}{c}\right)^{2} - m^{2}c^{2} - (P_{x} - qA_{x})^{2} - (P_{y} - qA_{y})^{2}}$

Curl in Frenet-Serret coordinates

$$\nabla \times \vec{A} = \frac{1}{1 + x / \rho} \left(\frac{\partial A_s}{\partial y} - \frac{\partial A_y}{\partial s} \right) \hat{x} + \frac{1}{1 + x / \rho} \left(\frac{\partial A_x}{\partial s} - \frac{\partial A_s}{\partial x} \right) \hat{y} + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{s}$$

• For static transverse magnetic fields

$$\phi = 0, \quad A_x = A_y = 0$$
$$B_x = \frac{1}{1 + x / \rho} \frac{\partial A_s}{\partial y}, \quad B_y = -\frac{1}{1 + x / \rho} \frac{\partial A_s}{\partial x}$$



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Hamiltonian in Standard Canonical Coordinates

• For static transverse magnetic fields

$$\phi = 0, \quad A_x = A_y = 0$$

$$\frac{H_s}{p_0} = -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \sqrt{\left(\frac{U}{p_0 c}\right)^2 - \left(\frac{mc}{p_0}\right)^2 - \left(\frac{p_x}{p_0}\right)^2 - \left(\frac{p_y}{p_0}\right)^2}$$

$$= -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \sqrt{\left(\frac{U}{p_0 c}\right)^2 - \left(\frac{mc}{p_0}\right)^2 - x'^2 - y'^2}$$

$$= H(x, x', y, y', t, -U / p_0; s)$$

$$p_x / p_0 \approx dx / ds = x', \quad p_y / p_0 \approx dy / ds = y'$$

• Canonical change of longitudinal coordinates

$$(t, -U / p_0) \rightarrow (z = s - v_0 t, \delta = \Delta p / p_0)$$

$$\tilde{H}(x, x', y, y', z, \delta; s) = H(x, x', y, y', t, -U / p_0; s) + \partial F_2(t, \delta; s) / \partial s$$

$$z = \partial F_2 / \partial \delta, \quad -U / p_0 = \partial F_2 / \partial t$$



Hamiltonian in Standard Canonical Coordinates

$$F_{2} = -\frac{U}{p_{0}}t + F(\delta, s)$$

$$\frac{U}{p_{0}} = \frac{U_{0}}{p_{0}}\left(1 + \frac{\Delta U}{U}\right) = \frac{c}{\beta_{0}}(1 + \beta_{0}^{2}\delta)$$

$$F_{2} = -\frac{c}{\beta_{0}}(1 + \beta_{0}^{2}\delta)t + \delta s + F(s)$$

$$F_{2} = \frac{c}{\beta_{0}}(1 + \beta_{0}^{2}\delta)\left(\frac{s}{\nu_{0}} - t\right) - \frac{s}{\beta_{0}^{2}} + s$$

• Hamiltonian in the new canonical longitudinal coordinates

$$\tilde{H} = -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \sqrt{\left(\frac{p}{p_0}\right)^2 - x'^2 - y'^2} + \frac{\partial F_2}{\partial s}$$
$$= -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \sqrt{1 + 2\delta + \delta^2 - x'^2 - y'^2} + 1 + \delta$$



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Hamiltonian in Standard Canonical Coordinates

• Expansion of the Hamiltonian keeping the lower-order terms

$$\begin{split} \tilde{H} &= -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \left(1 + \frac{1}{2} [2\delta + \delta^2 - (x'^2 + y'^2) + \ldots] - \frac{1}{8} [4\delta^2 + \ldots] + \ldots\right) + 1 + \delta \\ &= -\frac{qA_s}{p_0} - \left(1 + \frac{x}{\rho}\right) \left(1 + \delta - \frac{1}{2} (x'^2 + y'^2) + \ldots\right) + 1 + \delta \\ &= -\frac{qA_s}{p_0} + \frac{1}{2} (x'^2 + y'^2) - \frac{x}{\rho} - \frac{x\delta}{\rho} \end{split}$$



Symplectic Transformations and Matrices

• Hamilton's equations

$$H = H(x, P_x, y, P_y, t, -U; s), \quad \vec{X} = (x, P_x, y, P_y, t, -U)$$
$$\frac{dx_i}{ds} = \frac{\partial H}{\partial P_i}, \quad \frac{dP_i}{ds} = -\frac{\partial H}{\partial x_i}$$
$$\frac{dX_i}{ds} = \sum_{j=1}^6 S_{ij} \frac{\partial H}{\partial X_j}$$
$$S = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0\\ -1 & 0 & 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 1 & 0 & 0\\ 0 & 0 & -1 & 0 & 0 & 0\\ 0 & 0 & 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 0 & -1 & 0 \end{pmatrix}$$



Symplectic Transformations and Matrices

• Canonical coordinate transformation in passing through a beam line

$$\vec{X}_{1} = \vec{X}_{1}(\vec{X}_{0})$$

$$\frac{dX_{1i}}{ds} = \sum_{j} \frac{\partial X_{1i}}{\partial X_{0j}} \frac{dX_{0j}}{ds} = \sum_{j} M_{ij} \frac{dX_{0j}}{ds}$$

$$\frac{dX_{1i}}{ds} = \sum_{j} S_{ij} \frac{\partial H}{\partial X_{1j}} = \sum_{j,k} S_{ij} \frac{\partial H}{\partial X_{0k}} \frac{\partial X_{0k}}{\partial X_{1j}} = \sum_{j,k} S_{ij} \left(\left(M^{-1} \right)^{T} \right)_{jk} \frac{\partial H}{\partial X_{0k}}$$

$$\frac{dX_{1i}}{ds} = -\sum_{j,k} S_{ij} \left(\left(M^{-1} \right)^{T} \right)_{jk} S_{kl} \frac{dX_{0l}}{ds} = \sum_{j} M_{ij} \frac{dX_{0j}}{ds} \Longrightarrow$$

$$M = -S(M^{T})^{-1}S, \quad S = M^{T}SM$$

Definition of a symplectic matrix.



Symplectic Integration

• Expanding the equation of motion in the neighborhood of the reference trajectory $\hat{X}(s)$

$$\frac{d}{ds}(\hat{X}_{i} + \Delta X_{i}) = \sum_{j=1}^{6} S_{ij} \frac{\partial H}{\partial X_{j}}(\hat{X} + \Delta X) = \sum_{j=1}^{6} S_{ij} \left[\frac{\partial H}{\partial X_{j}}(\hat{X}) + \sum_{k=1}^{6} \frac{\partial^{2} H}{\partial X_{j} \partial X_{k}}(\hat{X}) \Delta X_{k} + \dots \right]$$
$$\frac{d\Delta X_{i}}{ds} = \sum_{j=1}^{6} \sum_{k=1}^{6} S_{ij} \frac{\partial^{2} H}{\partial X_{j} \partial X_{k}}(\hat{X}) \Delta X_{k} + \dots = \sum_{j=1}^{6} \sum_{k=1}^{6} S_{ij} C_{jk} \Delta X_{k} + \dots$$

• In matrix notation

$$\frac{d\Delta \bar{X}}{ds} = SC\Delta \bar{X}$$

• If C is constant

$$\Delta \vec{X}(s) = e^{SCs} \Delta \vec{X}(0) \implies M(s) = e^{SCs}$$

• If C is a function of s we approximate it in a piecewise constant fasion as

$$M(s) = e^{SC(s-ds)ds} \cdots e^{SC(2ds)ds} e^{SC(ds)ds} e^{SC(0)ds}$$



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Symplectic Matrices

• Since any 2*n*×2*n* symplectic matrix can be expressed in terms of a symmetric matrix it has the same number of degrees of freedom

$$\frac{(2n)^2 - 2n}{2} + 2n = (2n+1)n$$

E.g. a 4×4 symplectic matrix has 10 independent parameters.

• Choosing a basis for 4×4 symmetric matrices



Symplectic Matrices

• Any 4×4 symmetric matrix can be written in the form

$$C = \sum_{j=1}^{10} \alpha_j c_j$$

• Any 4×4 symplectic matrix can be written as

$$\exp(SC) = \exp\left(\sum_{j=1}^{10} \underbrace{Sc_j}_{G_j} \alpha_j\right) = \exp\left(\sum_{j=1}^{10} G_j \alpha_j\right)$$



Manipulations with Exponentials

 $\mathbf{Y} = \mathbf{V}$

• The Baker-Campbell-Hausdorff (BCH) formula

$$e^{X}e^{Y} = e^{Z}$$

$$Z = \log(e^{X}e^{Y}) = X + Y + \frac{1}{2}[X,Y] + \frac{1}{12}([X,X,Y] + [Y,Y,X]) + \frac{1}{24}[X,Y,Y,X] + \dots$$

$$[X,X,Y] \equiv [X,[X,Y]], \quad [X,Y,Y,X] \equiv [X,[Y,[Y,X]]]$$

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• The Zassenhaus formula

$$e^{(A+B)h} = e^{Ah}e^{Bh}e^{-[A,B]h^2/2}e^{(2[B,A,B]+[A,A,B])h^3/6}e^{O(h^4)}$$

Up to 2^{nd} order in h

$$e^{(A+B)h} = e^{Ah/2}e^{Bh}e^{Ah/2} + O(h^3)$$

$$M(h) = e^{SCh} = \exp\left(\sum_{j=1}^{10} \alpha_j G_j h\right) = \exp\left(\alpha_1 G_1 h + \sum_{j=2}^{10} \alpha_j G_j h\right)$$
$$= \underbrace{\exp\left(\alpha_1 G_1 h / 2\right)}_{\text{half-step drift}} \underbrace{\exp\left(\sum_{j=2}^{10} \alpha_j G_j h\right)}_{\text{thin element kick}} \underbrace{\exp\left(\alpha_1 G_1 h / 2\right)}_{\text{half-step drift}}$$



Symplectic Integrator

• The matrix representing a canonical coordinate transformation over a small step during which the fields can be considered constant can be represented as a thin kick sandwiched between two drifts with all coefficients determined by the Hamiltonian

$$M(h) = \underbrace{\exp(\alpha_{1}G_{1}h/2)}_{\text{half-step drift}} \underbrace{\exp\left(\sum_{j=2}^{10}\alpha_{j}G_{j}h\right)}_{\text{thin element kick}} \underbrace{\exp(\alpha_{1}G_{1}h/2)}_{\text{half-step drift}}$$

$$G_{1} = Sc_{1} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\exp(\alpha_{1}G_{1}h/2) = \begin{pmatrix} 1 & \alpha_{1}h/2 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & \alpha_{1}h/2 \\ 0 & 0 & 0 & 1 \end{pmatrix} + O(h^{3})$$

• This is the basis of symplectic drift-kick codes, kicks can be non-linear, e.g. for sextupoles, octupoles, etc.



Time-Symmetric Integrators

• Apply the BCH formula to the time symmetric product

$$e^{W} = e^{Xh}e^{Yh}e^{Xh} = \exp(X + Y + \frac{1}{2}[X,Y] + \frac{1}{12}([X,X,Y] + [Y,Y,X]) + \frac{1}{24}[X,Y,Y,X])e^{Xh}$$

$$= \exp\{(X+Y)h + \frac{1}{2}[X,Y]h^{2} + \frac{1}{12}([X,X,Y] + [Y,Y,X])h^{3} + \frac{1}{24}[X,Y,Y,X]h^{4} + Xh$$

$$+ \frac{1}{2}[X+Y,X]h^{2} + \frac{1}{4}[[X,Y],X]h^{3} + \frac{1}{24}([[X,X,Y],X] + [[Y,Y,X],X])h^{4}$$

$$+ \frac{1}{12}([X+Y,X+Y,X] + [X,X,X+Y])h^{3} + \frac{1}{24}[X,X,X,Y]h^{4} + O(h^{5})\}$$

$$= \exp\{(2X+Y)h + \frac{1}{6}([Y,Y,X] - [X,X,Y])h^{3} + O(h^{5})\}$$



Time-Symmetric Integrators

• If an integrator

$$I(h) = e^{g_1 h + g_2 h^2 + g_3 h^3 + \dots}$$

is time reversible then

$$I(h)I(-h) = 1$$

• Applying the BCH formula gives

$$I(h)I(-h) = e^{g_1h + g_2h^2 + g_3h^3 + \dots} e^{-g_1h + g_2h^2 - g_3h^3 + \dots} = e^{2g_2h^2 + O(h^3)} = 1 \implies g_2 = 0$$

• Repeating we find by induction that all even powers vanish

$$g_{2j} = 0$$

i.e. $\log(I(h))$ must be an odd function of *h*.



Higher-Order Integrators

• Higher-order integrators may be constructed from the 2nd-order integration function

$$I_{2}(h) = e^{Ah/2}e^{Bh}e^{Ah/2} = e^{g_{1}h + g_{3}h^{3} + .}$$

• 4th-order integrator may be constructed using time-symmetric product of 2nd-order integrators

$$I_4(h) = I_2(ah)I_2(bh)I_2(ah)$$
$$I_4(h) = e^{(2a+b)g_1h + (2a^3+b^3)g_3h^3 + \dots} = e^{(A+B)h + O(h^5)}$$

• To 4th-order this requires

$$\begin{cases} 2a+b=1\\ 2a^3+b^3=0 \end{cases} \implies a=\frac{1}{2-2^{1/3}}, \quad b=-\frac{2^{1/3}}{2-2^{1/3}} \end{cases}$$



Symplectification Algorithm

• A symplectic matrix *M* may be written in the form

$$M = (I + SW)(I - SW)^{-1}$$

if and only if *W* is a symmetric matrix.

- If W is symmetric $M^{T}SM = (I - W^{T}S^{T})^{-1}(I + W^{T}S^{T})S(I + SW)(I - SW)^{-1}$ $= (I + WS)^{-1}(I - WS)S(I + SW)(I - SW)^{-1} = (I + WS)^{-1}(I - WS)(I + WS)S(I - SW)^{-1}$ $= (I + WS)^{-1}(I + WS)(I - WS)S(I - SW)^{-1} = (I + WS)^{-1}(I + WS)S(I - SW)(I - SW)^{-1}$ = S
- If *M* is symplectic and W = P + Q, $W = P^T Q^T$

$$M^{T}SM = S = (I - W^{T}S^{T})^{-1}(I + W^{T}S^{T})S(I + SW)(I - SW)^{-1}$$

= $(I - W^{T}S^{T})^{-1}(S + P - Q - P - Q + W^{T}SW)(I - SW)^{-1}$
= $(I - W^{T}S^{T})^{-1}[(S - W^{T})(I - SW) - 4Q](I - SW)^{-1}$
= $S - 4(I - W^{T}S^{T})^{-1}Q(I - SW)^{-1} \implies Q = 0$



Symplectification Algorithm

• Symmetric matrix from a symplectic matrix

$$W = S(I+M)^{-1}(I-M)$$

• For an almost symplectic matrix calculate the almost symmetric matrix

$$W_0 = S(I + M_0)^{-1}(I - M_0)$$

• Symmetrize the almost symmetric matrix

$$W_1 = (W_0 + W_0^T) / 2$$

• Obtain a symplectic approximation of the original matrix

$$M_1 = (I + SW_1)(I - SW_1)^{-1}$$



Example: Sector Dipole Magnet

• Sector dipole magnet:

$$\vec{B} = \begin{cases} B_0 \,\hat{y}, \text{ for } 0 < s < L \\ 0, \text{ elsewhere} \end{cases}$$

$$B_{y} = -\frac{1}{1+x/\rho} \frac{\partial A_{s}}{\partial x} \implies A_{s} = -B_{0} \left(x + \frac{x^{2}}{2\rho} \right)$$
$$\tilde{H} = \left(\frac{x}{\rho} + \frac{x^{2}}{2\rho^{2}} \right) + \frac{1}{2} (x'^{2} + y'^{2}) - \frac{x}{\rho} - \frac{x\delta}{\rho} = \frac{x^{2}}{2\rho^{2}} + \frac{1}{2} (x'^{2} + y'^{2}) - \frac{x\delta}{\rho}$$

Hessian matrix of the Hamiltonian

$$C = \frac{\partial H}{\partial X_i \partial X_j} \approx \begin{pmatrix} 1/\rho^2 & 0 & 0 & 0\\ 0 & 1 & 0 & 0\\ 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix} = c_1 + \frac{1}{2\rho^2}(c_3 + c_4), \quad SC = \begin{pmatrix} 0 & 1 & 0 & 0\\ -1/\rho^2 & 0 & 0 & 0\\ 0 & 0 & 0 & 1\\ 0 & 0 & 0 & 1\\ 0 & 0 & 0 & 0 \end{pmatrix}$$
$$M(s) = e^{SCs} = \sum_{n=0}^{\infty} \frac{(SCs)^n}{n!} = \begin{pmatrix} \cos(s/\rho) & \rho \sin(s/\rho) & 0 & 0\\ -\sin(s/\rho)/\rho & \cos(s/\rho) & 0 & 0\\ 0 & 0 & 1 & s\\ 0 & 0 & 0 & 1 \end{pmatrix}$$
USPAS: Lecture on Hamiltonian Dynamics Vasility Morozov, January 2015